No. FEB1CECE2 2016.04

This manual contains instructions for communication functions of the FEB-102-EC ...

To prevent accidents arising from the misuse of this instrument, please ensure the operator receives this manual.



Warning

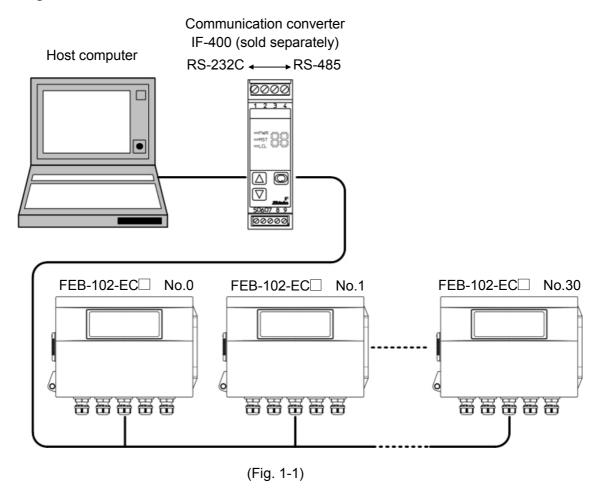
Turn the power switch of the instrument off before wiring or checking.

Working on or touching the terminal with the power switched on may result in severe injury or death due to electrical shock.

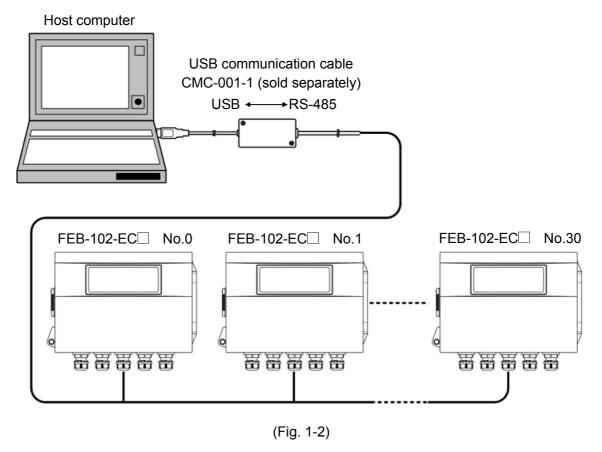
1. System Configuration

The following shows a system configuration example using the communication converter IF-400 or USB Communication Cable CMC-001-1.

When Using the Communication Converter IF-400



When Using the USB Communication Cable CMC-001-1



2. Wiring

Wiring example is shown using the communication converter IF-400 or USB communication cable CMC-001-1

When using the communication converter IF-400

Connection between the communication converter IF-400 and FEB-102-EC□

By using communication cable CDM (sold separately),

Connect the cable modular jack to the IF-400 modular jack, and Y terminal 4 to FEB-102-EC 10 [YA(-)].

Connect Y terminal ③ to FEB-102- EC ☐ ① [YB(+)].

Connect Y terminals ① and ⑥ to FEB-102- EC □ ② [COM].

Connection between FEB-102- EC□ units

By using the shield wire, connect $^{\textcircled{10}}$ [YA(-)] to $^{\textcircled{10}}$ [YA(-)], $^{\textcircled{11}}$ [YB(+)] to $^{\textcircled{11}}$ [YB(+)], and $^{\textcircled{12}}$ [COM] to $^{\textcircled{12}}$ [COM].

D-sub 9-pin connector D-sub 25-pin connector Communication Communication converter converter IF-400 Host computer IF-400 Host computer (sold separately) (sold separately) TXD 3 TXD 2 RXD 2 RXD 3 0000 0000 7 5 GND SG 1 2 3 4 Shield FG DCD Shield 1 1 wire wire FG DTR 4 RTS 4 CTS 5 DSR 6 RTS 7 DSR CTS DTR 20 8 RI 9 CD 8 CDM (Sold separately) CDM (Sold separately) FEB-102-EC□ No. 0 FEB-102-EC□ No. 30 FEB-102-EC□ No. 1 (10)(11)(12) (10)(11)(12) 10(11(12) Shield Shield wire wire FG

(Fig. 2-1)

When Using the USB Communication Cable CMC-001-1

Connection between the host computer and FEB-102-EC□

By using the USB communication cable CMC-001-1 (sold separately),

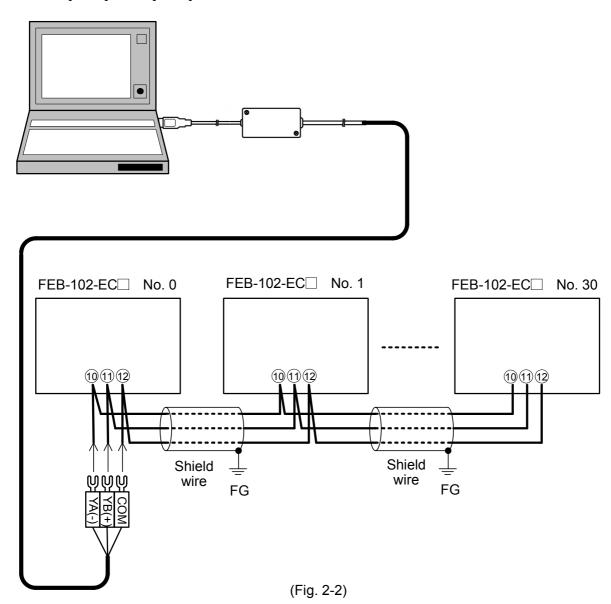
Connect Y terminal [YA(-)] to FEB-102-EC□ ⁽¹⁾ [YA(-)].

Connect Y terminal [YB(+)] to FEB-102-EC□ ¹ [YB(+)].

Connect Y terminal [COM] to FEB-102-EC□ ¹ [COM].

Connection between FEB-102-EC□ units

By using the shield wire, connect $^{\textcircled{10}}$ [YA(-)] to $^{\textcircled{10}}$ [YA(-)], $^{\textcircled{1}}$ [YB(+)] to $^{\textcircled{1}}$ [YB(+)], and $^{\textcircled{12}}$ [COM] to $^{\textcircled{12}}$ [COM].



Shield Wire

Connect only one end of the shield to the FG terminal to avoid a ground loop. If both ends of the shield wire are connected to the FG terminal, the circuit will be closed, resulting in a ground loop. This may cause noise. Be sure to ground the FG terminal.

Recommended cable: OTSC-VB 2PX0.5SQ (made by Onamba Co., Ltd.) or equivalent (use a twisted pair cable.)

Terminator (Terminal Resistor)

Communication converter IF-400 (sold separately) has a built-in terminator.

The terminator is mounted at the end of the wire when connecting a personal computer with multiple peripheral devices. The terminator prevents signal reflection and disturbance.

Do not connect a terminator to the communication line because each FEB-102-EC has built-in pull-up and pull-down resistors instead of a terminator.

3. Communication Settings

Communication parameters can be set in the Communication Group.

To enter the Communication Group, follow the procedure below.

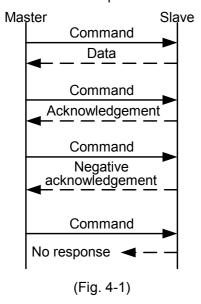
- (1) **G_PH** Press the key once in Conductivity/Temperature Display Mode.
- (2) G-COM Press the \Box key as many times as necessary until the left characters appear.
- (3) **CMSL** Press the set key once. The unit enters Communication Group, and "Communication protocol" appears.
- (4) Set each setting items using the \triangle or ∇ key, and register the value with the \square key.

| Character | Setting Item, Function, Setting Range | Factory Default |
|-----------|--|-----------------|
| CMSL | Communication protocol | Shinko protocol |
| NOML | Selects communication protocol. NOML : Shinko protocol MODA : Modbus ASCII mode | |
| | MODR : Modbus RTU mode | |
| CMNO | Instrument number | 0 |
| 0 | Sets the instrument number of this unit. (The instrument n by one when multiple instruments are connected in Serial communication is not possible.) Setting range: 0 to 95 | |
| CMSP | Communication speed | 9600 bps |
| 9600 | Selects a communication speed equal to that of the host of the post of the po | computer. |
| CMFT | Data bit/Parity | 7 bits/Even |
| 7EVN | Selects data bit and parity. BNON:: 8 bits/No parity 7NON:: 7 bits/No parity BEVN:: 8 bits/Even 7EVN:: 7 bits/Even 80DD:: 8 bits/Odd 70DD:: 7 bits/Odd | |
| CMST | Stop bit | 1 bit |
| 1 | Selects the stop bit. 1 : 1 bit 2 : 2 bits | |

(5) Press the key once. The unit will revert to Conductivity/Temperature Display Mode.

4. Communication Procedure

Communication starts with command transmission from the host computer (hereafter Master) and ends with the response of the FEB-102-EC \square (hereafter Slave).



Response with data

When the master sends the reading command, the slave responds with the corresponding set value or current status.

Acknowledgement

When the master sends the setting command, the slave responds by sending acknowledgement after the processing is terminated.

Negative acknowledgement

When the master sends a non-existent command or value out of the setting range, the slave returns a negative acknowledgement.

No response

The slave will not respond to the master in the following cases:

- · Global address (Shinko protocol) is set.
- Broadcast address (Modbus protocol) is set.
- Communication error (framing error, parity error)
- · Checksum error (Shinko protocol),
- LRC discrepancy (Modbus ASCII mode),
- CRC-16 discrepancy (Modbus RTU mode)

Communication Timing of the RS-485

Master Side (Take note while programming)

When the master starts transmission through the RS-485 communication line, the master is arranged so as to provide an idle status (mark status) transmission period of 1 or more characters before sending the command to ensure synchronization on the receiving side.

Set the program so that the master can disconnect the transmitter from the communication line within a 1 character transmission period after sending the command in preparation for reception of the response from the slave.

To avoid collision of transmissions between the master and the slave, send the next command after carefully checking that the master has received the response.

If a response to the command is not returned due to communication errors, set the Retry Processing to send the command again. (It is recommended to execute Retry twice or more.)

Slave Side

When the slave starts transmission through the RS-485 communication line, the slave is arranged so as to provide an idle status (mark status) transmission period of 1 or more characters before sending the response to ensure synchronization on the receiving side.

The slave is arranged so as to disconnect the transmitter from the communication line within a 1 character transmission period after sending the response.

5. Shinko Protocol

5.1 Transmission Mode

Shinko protocol is composed of ASCII codes.

Hexadecimal (0 to 9, A to F), which is divided into high order (4-bit) and low order (4-bit) out of 8-bit binary data in command is transmitted as ASCII characters.

Data format Start bit: 1 bit

Data bit: 7 bits Parity: Even Stop bit: 1 bit

Error detection: Checksum

5.2 Command Configuration

All commands are composed of ASCII.

The data (set value, decimal number) is represented by hexadecimal numbers.

Negative numbers are represented in 2's complement.

Numerals written below the command represent the number of characters.

(1) Setting Command

| Header (02H) | Address | Sub address (20H) | Command type (50H) | Data item | Data | Checksum | Delimiter (03H) |
|-----------------|---------|-------------------------|--------------------|--------------|------|----------|--------------------|
| 1 | 1 | 1 | 1 | 4 | 4 | 2 | 1 |

(2) Reading Command

| Header (02H) | Address | Sub address (20H) | Command type (20H) | Data item | Checksum | Delimiter (03H) |
|-----------------|---------|-------------------------|-----------------------|--------------|----------|--------------------|
| 1 | 1 | 1 | 1 | 4 | 2 | 1 |

(3) Response with Data

| eader 06H) | Address | Sub address (20H) | Command type (20H) | Data item | Data | Checksum | Delimiter (03H) |
|---------------|---------|-------------------------|-----------------------|--------------|------|----------|--------------------|
| 1 | 1 | 1 | 1 | 4 | 4 | 2 | 1 |

(4) Acknowledgement

| Header (06H) | Address | Checksum | Delimiter (03H) | |
|-----------------|---------|----------|--------------------|--|
| 1 | 1 | 2 | 1 | |

(5) Negative Acknowledgement

| | Header (15H) | Address | Error code | Checksum | Delimiter (03H) |
|---|-----------------|---------|---------------|----------|--------------------|
| , | 1 | 1 | 1 | 2 | 1 |

Header: Control code to represent the beginning of the command or the response.

ASCII codes are used.

Setting command, Reading command: STX (02H) fixed Response with data, Acknowledgement: ACK (06H) fixed Negative acknowledgement: NAK (15H) fixed

Instrument number (Address): Numbers by which the master discerns each slave.

Instrument numbers 0 to 94 and Global address 95.

ASCII codes (20H to 7FH) are used by adding 20H to instrument numbers 0 to 95

(00H to 5FH).

95 (7FH) is called the Global address, which is used when the same command is sent

to all the slaves connected. However, a response is not returned.

Sub address: 20H fixed

Command type: Code to discern Setting command (50H) and Reading command (20H)

Data item: Classification of the command object.

Composed of 4-digit hexadecimal numbers, using ASCII.

[Refer to "7. Communication Command Table" (pp.13 to 22).]

Data: The contents of data (set value) differ depending on the setting command.

Composed of 4-digit hexadecimal numbers, using ASCII. [Refer to "7. Communication Command Table" (pp.13 to 22).]

Checksum: 2-character data to detect communication errors. (Refer to "5.3 Checksum Calculation".)

Delimiter: Control code to represent the end of command.

ASCII code ETX (03H) fixed

Error code: Represents an error type using ASCII.

1 (31H)----Non-existent command

2 (32H)----Not used

3 (33H)----Setting outside the setting range

4 (34H)-----Status unable to be set (e.g. During Conductivity or Temperature Calibration

Mode)

5 (35H)-----During setting mode by keypad operation

5.3 Checksum Calculation

Checksum is used to detect receiving errors in the command or data.

Set the program for the master side as well to calculate the checksum of the response data from the slaves so that communication errors can be checked.

The ASCII code (hexadecimal) corresponding to the characters which range from the address (instrument number) to that before the checksum is converted to binary notation, and the total value is calculated.

The lower one byte of the total value is converted to 2's complement, and then to hexadecimal numbers, that is, ASCII code for the checksum.

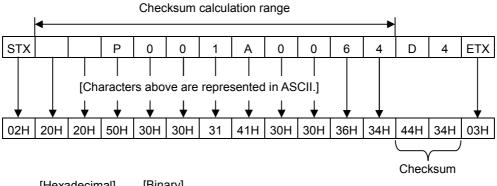
Checksum Calculation Example

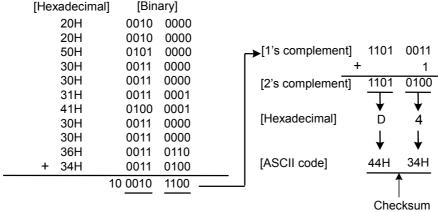
Data item 001AH (EVT1 value): 1.00 (0064H)

Address (instrument number): 0 (20H)

- 1's complement: Reverse each binary bit. 0 will become 1 and vice versa.
- 2's complement: Add 1 to 1's complement.

[e.g.]





(Fig. 5.3-1)

6. Modbus Protocol

6.1 Transmission Mode

There are 2 transmission modes (ASCII and RTU) in Modbus protocol.

6.1.1 ASCII Mode

Hexadecimal (0 to 9, A to F), which is divided into high order (4-bit) and low order (4-bit) out of 8-bit binary data in command is transmitted as ASCII characters.

Data format Start bit: 1 bit

Data bit: 7 bits

Parity: Even (No parity, Odd) (Selectable)

Stop bit: 1 bit (2 bits) (Selectable)

Error detection: LRC (Longitudinal Redundancy Check)

6.1.2 RTU Mode

8-bit binary data in command is transmitted as it is.

Data format Start bit: 1 bit

Data bit: 8 bits

Parity: No parity (Even, Odd) (Selectable)

Stop bit: 1 bit (2 bits) (Selectable)

Error detection: CRC-16 (Cyclic Redundancy Check)

6.2 Data Communication Interval

6.2.1 ASCII Mode

1 second or less

Max.1 second of interval between ASCII mode characters

6.2.1 RTU Mode

3.5 character transmission times or less

To transmit continuously, an interval between characters which consist of one message, must be within 3.5 character transmission times.

If an interval lasts longer than 3.5 character transmission times, FEB-102-EC \square assumes that transmission from the master is finished, which results in a communication error, and will not return a response.

6.3 Message Configuration

6.3.1 ASCII Mode

ASCII mode message is configured to start by Header [: (colon) (3AH)] and end by Delimiter [CR (carriage return) (0DH) + LF (Line feed) (0AH)].

| Header | Slave | Function | Data | Error check | Delimiter | Delimiter |
|--------|---------|----------|------|-------------|-----------|-----------|
| (:) | address | code | Dala | LRC | (CR) | (LF) |

6.3.2 RTU Mode

RTU mode is configured to start after idle time is processed for more than 3.5 character transmissions, and end after idle time is processed for more than 3.5 character transmissions.

| 3.5 idle | Slave | Function | Data | Error check | 3.5 idle |
|------------|---------|----------|------|-------------|------------|
| characters | address | code | Data | CRC-16 | characters |

6.3.3 Message Details

(1) Slave Address

Slave address is an individual instrument number on the slave side, and is set within the range 0 to 95 (00H to 5FH). The master identifies slaves by the slave address of the requested message.

The slave informs the master which slave is responding to the master by placing its own address in the response message.

Slave address 00H (Broadcast address) can identify all the slaves connected. However slaves do not respond.

(2) Function Code

The function code is the command code for the slave to undertake one of the following actions.

(Table 6.3.3-1)

| Function Code | Contents |
|----------------------|---|
| 03 (03H) | Reading the set value and information from slaves |
| 06 (06H) | Setting to slaves |

The Function code is used to discern whether the response is normal (acknowledgement) or if any error (negative acknowledgement) has occurred when the slave returns the response message to the master.

When acknowledgement is returned, the slave simply returns the original function code.

When negative acknowledgement is returned, the MSB of the original function code is set as 1 for the response.

(For example, if the master sends request message setting 10H to the function code by mistake, slave returns 90H by setting the MSB to 1, because the former is an illegal function.)

For negative acknowledgement, the exception codes below are set to the data of the response message, and returned to the master in order to inform it of what kind of error has occurred. (Table 6.3.3-2)

(Table 6.3.3-2)

| Exception Code Contents | | | |
|-------------------------|--|--|--|
| 1 (01H) | Illegal function (Non-existent function) | | |
| 2 (02H) | Illegal data address (Non-existent data address) | | |
| 3 (03H) | Illegal data value (Value out of the setting range) | | |
| 17 (11H) | Shinko protocol error code 4 [Status unable to be set. (e.g.) During Conductivity or | | |
| | Temperature Calibration Mode] | | |
| 18 (12H) | Shinko protocol error code 5 (During setting mode by keypad operation) | | |

(3) Data

Data differs depending on the function code.

A request message from the master is composed of a data item, amount of data, and setting data. A response message from the slave is composed of a number of bytes, data and exception codes in negative acknowledgements. [Refer to "7. Communication Command Table" (pp.13 to 22).] The effective range of data is -32768 to 32767 (8000H to 7FFFH).

(4) Error Check

Error check differs depending on the ASCII Mode and RTU mode.

ASCII Mode

After calculating LRC (Longitudinal Redundancy Check) from the slave address to the end of data, the calculated 8-bit data is converted to two ASCII characters, and are appended to the end of message.

How to calculate LRC

- ① Create a message in RTU mode.
- ② Add all the values from the slave address to the end of data. This is assumed as X.
- Make a complement for X (bit reverse). This is assumed as X.
- 4 Add a value of 1 to X. This is assumed as X.
- (5) Set X as an LRC to the end of the message.
- 6 Convert the whole message to ASCII characters.

RTU Mode

After calculating CRC-16 (Cyclic Redundancy Check) from the slave address to the end of the data, the calculated 16-bit data is appended to the end of message in sequence from low order to high order.

How to calculate CRC-16

In the CRC-16 system, the information is divided by the polynomial series. The remainder is added to the end of the information and transmitted. The generation of a polynomial series is as follows. (Generation of polynomial series: $X^{16} + X^{15} + X^2 + 1$)

- 1 Initialize the CRC-16 data (assumed as X) (FFFFH).
- ② Calculate exclusive OR (XOR) with the 1st data and X. This is assumed as X.
- 3 Shift X one bit to the right. This is assumed as X.
- 4 When a carry is generated as a result of the shift, XOR is calculated by X of 3 and the fixed value (A001H). This is assumed as X. If a carry is not generated, go to step 5.
- ⑤ Repeat steps ③ and ④ until shifting 8 times.
- 6 XOR is calculated with the next data and X. This is assumed as X.
- 7 Repeat steps 3 to 5.
- 8 Repeat steps 3 to 5 up to the final data.
- Set X as CRC-16 to the end of message in seguence from low order to high order.

6.4 Message Example

6.4.1 ASCII Mode

Numerals written below the command represent the number of characters.

① Reading [Slave address 1, Data item 0080H (Conductivity)]

· A request message from the master

Amount of data means how many data items are to be read. It is fixed as (30H 30H 30H 31H).

| Header | Slave | Function | Data item | Amount of data | Error check | Delimiter |
|--------|-----------|-----------|-------------------|-------------------|-------------|-----------|
| | address | code | [0080H] | [0001H] | LRC | |
| (3AH) | (30H 31H) | (30H 33H) | (30H 30H 38H 30H) | (30H 30H 30H 31H) | (37H 42H) | (0DH 0AH) |
| 1 | 2 | 2 | 4 | 4 | 2 | 2 |

• Response message from the slave in normal status [1.00 mS/cm (0064H)]

The number of response bytes means the number of bytes of data which have been read. It is fixed as (30H 32H).

| Head (3AH | er Slave address (30H 31H) | Function code (30H 33H) | Number of response bytes [02H] (30H 32H) | Data [0064H] (30H 30H 36H 34H) | Error check LRC (39H 36H) | Delimiter (0DH 0AH) |
|--------------|----------------------------------|-------------------------------|---|--------------------------------------|---------------------------------|------------------------|
| 1 | 2 | 2 | 2 | 4 | 2 | 2 |

• Response message from the slave in exception (error) status (When a data item is incorrect)
The function code MSB is set to 1 for the response message in exception (error) status (83H is returned).

The exception code 02H (Non-existent data address) is returned (error).

| | opas. coas | · •=:: (:::•:: • | | | |
|--------|------------|------------------|----------------|-------------|-----------|
| Header | Slave | Function | Exception code | Error check | Delimiter |
| | address | code | [02H] | LRC | |
| (3AH) | (30H 31H) | (38H 33H) | (30H 32H) | (37H 41H) | (0DH 0AH) |
| 1 | 2 | 2 | 2 | 2 | 2 |

② Setting [Slave address 1, Data item 001AH (EVT1 value) 1.00 (0064H)]

• A request message from the master

| Header | Slave | Function | Data item | Data | Error check | Delimiter |
|--------|-----------|-----------|-------------------|-------------------|-------------|-----------|
| | address | code | [001AH] | [0064H] | LRC | |
| (3AH) | (30H 31H) | (30H 36H) | (30H 30H 31H 41H) | (30H 30H 36H 34H) | (37H 42H) | (0DH 0AH) |
| 1 | 2 | 2 | 1 | Λ | 2 | 2 |

• Response message from the slave in normal status

| Header | Slave | Function | Data item | Data | Error check | Delimiter |
|--------|-----------|-----------|-------------------|-------------------|-------------|-----------|
| | address | code | [001AH] | [0064H] | LRC | |
| (3AH) | (30H 31H) | (30H 36H) | (30H 30H 31H 41H) | (30H 30H 36H 34H) | (37H 42H) | (0DH 0AH) |
| 1 | 2 | 2 | 4 | 4 | 2 | 2 |

• Response message from the slave in exception (error) status (When a value out of the setting range is set.)

The function code MSB is set to 1 for the response message in exception (error) status (86H is returned.).

The exception code 03H (Value out of the setting range) is returned (error).

| The exception code con (value out of the cotting range) is retained (enci | | | | | | | |
|---|-----------|-----------|----------------|-------------|-----------|--|--|
| Header | Slave | Function | Exception code | Error check | Delimiter | | |
| | address | code | [03H] | LRC | | | |
| (3AH) | (30H 31H) | (38H 36H) | (30H 33H) | (37H 36H) | (0DH 0AH) | | |
| 1 | 2 | 2 | 2 | 2 | 2 | | |

6.4.2 RTU Mode

Numerals written below the command represent the number of characters.

- ① Reading [Slave address 1, Data item 0080H (Conductivity)]
- A request message from the master

Amount of data means how many data items are to be read. It is fixed as (0001H).

| 3.5 idle | Slave | Function | Data item | Amount of data | Error check CRC-16 | 3.5 idle |
|------------|------------------|---------------|-----------|----------------|-----------------------|------------|
| characters | address (01H) | code (03H) | (0080H) | (0001H) | (85E2H) | characters |
| | 1 | 1 | 2 | 2 | 2 | |

• Response message from the slave in normal status [1.00 mS/cm (0064H)]

The number of response bytes means the number of bytes of data which has been read. It is

fixed as (02H).

| 3.5 idle | Slave address | Function code | Number of response bytes | Data | Error check CRC-16 | 3.5 idle |
|------------|------------------|---------------|--------------------------|---------|-----------------------|------------|
| characters | (01H) | (03H) | (02H) | (0064H) | (B9AFH) | characters |
| | 1 | 1 | 1 | 2 | 2 | |

• Response message from the slave in exception (error) status (When a data item is incorrect)
The function code MSB is set to 1 for the response message in exception (error) status (83H is returned).

The exception code (02H: Non-existent data address) is returned (error).

| 3.5 idle | Slave | Function | Exception code | Error check | 3.5 idle |
|------------|------------------|---------------|----------------|-------------------|------------|
| characters | address (01H) | code (83H) | (02H) | CRC-16 (C0F1H) | characters |
| | 1 | 1 | 1 | 2 | |

② Setting (Slave address 1, Data item 001AH (EVT1 value) 1.00 (0064H)]

• A request message from the master

| 3.5 idle | Slave address | Function code | Data item | Data | Error check CRC-16 | 3.5 idle |
|------------|------------------|---------------|-----------|---------|-----------------------|------------|
| characters | (01H) | (06H) | (001AH) | (0064H) | (A9E6H) | characters |
| | 1 | 1 | 2 | 2 | 2 | |

• Response message from the slave in normal status

| 3.5 idle | Slave | Function | Data item | Data | Error check | 3.5 idle |
|------------|---------|----------|-----------|---------|-------------|------------|
| | address | code | | | CRC-16 | 1 |
| characters | (01H) | (06H) | (0008H) | (0064H) | (A9E6H) | characters |
| | 1 | 1 | 2 | 2 | 2 | |

• Response message from the slave in exception (error) status (When a value out of the setting range is set) The function code MSB is set to 1 for the response message in exception (error) status (86H is returned.).

The exception code (03H: Value out of the setting range) is returned (error).

| 3.5 idle | Slave | Function | Exception code | Error check | 3.5 idle |
|------------|---------|----------|----------------|-------------|------------|
| | address | code | | CRC-16 | |
| characters | (01H) | (86H) | (03H) | (0261H) | characters |
| | 1 | 1 | 1 | 2 | |

7. Communication Command Table

7.1 Note on Setting and Reading Commands

- The data (set value, decimal) is converted to hexadecimal numbers.
- Negative numbers are represented in 2's complement.
- When connecting multiple slaves, the address (instrument number) must not be duplicated.
- User save area 1 to 10 (0200H to 0209H) can be read or set in 1 word units. Effective range of data is -32768 to 32767 (8000H to 7FFFH).
- Even if EVT3 or EVT4 options are not ordered, setting or reading via software communication will be possible. However, EVT3 and EVT4 command contents will not function.
- Do not use undefined Data items. If they are used, negative acknowledgement will be returned or a random value will be written or read, resulting in malfunction.
- Modbus protocol uses Holding Register addresses. The Holding Register addresses are created as follows. A Shinko command data item is converted to decimal number, and the offset of 40001 is added. The result is the Holding Register address.
 - Using Data item 001AH (EVT1 value) as an example: The Data item in the sending message is 001AH, however, the Modbus protocol Holding Register address is 40027 (26 + 40001).

(1) Setting Command

- Up to 1,000,000 (one million) entries can be stored in non-volatile IC memory. If the number of settings exceeds the limit, the data will not be saved. So, do not change the set values frequently via software communication. (If a value set via software communication is the same as the value before the setting, the value will not be written in non-volatile IC memory.)
- Be sure to select Lock 3 when changing the set value frequently via software communication. If Lock 3 is selected, all set values –except Sensor cell constant, Unit selection, Measurement range, RTD, Conductivity Zero adjustment value, Conductivity Span adjustment value, Temperature calibration value, Transmission output 1 Zero adjustment value, Transmission output 1 Span adjustment value, Transmission output 2 Zero adjustment value, Transmission output 2 Span adjustment value can be temporarily changed. However, they revert to their previous value after the power is turned off because they are not saved in the non-volatile IC memory.
- Do not change setting items (EVT1, EVT2, EVT3, EVT4 types). If they are changed, they will affect other setting items.
- Setting range of each item is the same as that of keypad operation.
- When the data (set value) has a decimal point, a whole number (hexadecimal) without a decimal point is used.
- If EVT type is changed at Data item 0019H (EVT1 type), 0027H (EVT2 type), 0035H (EVT3 type) or 0043H (EVT4 type), then EVT1, EVT2, EVT3 or EVT4 value will default to 0 (zero). The output status of EVT1, EVT2, EVT3 or EVT4 will also be initialized.
- Settings via software communication are possible while in Set value lock status.
- The Instrument Numbers and Communication Speed of the slave cannot be set by the software communication. They can only be set via the keypad.
- When sending a command by Global address [95 (7FH), Shinko protocol] or Broadcast address [0 (00H), Modbus protocol], the same command is sent to all the slaves connected. However, the response is not returned.

(2) Reading Command

• When the data (set value) has a decimal point, a whole number (hexadecimal) without a decimal point is used for a response.

7.2 Setting/Reading Command

| Shinko Command Type | Modbus Function Code | | Data Item | Data |
|---------------------------|----------------------------|-------|----------------------|----------------|
| 50H/20H | 06H/03H | 0001H | Sensor cell constant | (FEB-102-ECH) |
| | | | | 0000H: 1.0/cm |
| | | | | 0001H: 10.0/cm |
| | | | | (FEB-102-ECM) |
| | | | | 0000H: 0.01/cm |
| | | | | 0001H: 0.1/cm |
| | | | | 0002H: 1.0/cm |

| Shinko | Modbus | | | | | | | |
|-----------|-----------|--------|--------|----------------------------|--------------------------------|---------------|--|--|
| Command | | | | Data Item | | | Data | |
| Type | Code | | | | | | | |
| 50H/20H | 06H/03H | 0002H | Cell c | onstant correction value | | Set val | lue, Decimal point ignored. | |
| 50H/20H | 06H/03H | 0003H | Unit s | election | | (FEB-102-ECH) | | |
| | | | | | | 0000H | : Conductivity (mS/cm) | |
| | | | | | | | : Conductivity (S/m) | |
| | | | | | | | : Seawater salinity (%) | |
| | | | | | | | : NaCl salinity (%) | |
| | | | | | | | : TDS conversion (g/L) | |
| | | | | | | | 102-ECM) | |
| | | | | | | • | : Conductivity (#S/cm) | |
| | | | | | | | • | |
| | | | | | | | : Conductivity (mS/m) | |
| 5011/0011 | 0011/0011 | 000411 | | | | 0002H | : TDS conversion (mg/L) | |
| 50H/20H | 06H/03H | 0004H | | urement range | | | | |
| | | | , | 3-102-ECH) | | | | |
| | | | | ta differs depending on th | ne sel | ection of | sensor cell constant | |
| | | | an | d unit. | | | | |
| | | | | When Sensor cell cons | | | | |
| | | | | Unit | | Data | Measurement Range | |
| | | | | | | 000H | 0.00 to 20.00 mS/cm | |
| | | | | Conductivity (mS/cm) | | 001H | 0.0 to 200.0 mS/cm | |
| | | | | | | 002H | 0.0 to 500.0 mS/cm | |
| | | | | | | 003H | 0 to 500 mS/cm | |
| | | | | | | 000H | 0.000 to 2.000 S/m | |
| | | | | Conductivity | | 001H | 0.00 to 20.00 S/m | |
| | | | | (S/m, mS/m) | | 002H | 0.00 to 50.00 S/m | |
| | | | | | | 003H | 0.0 to 50.0 S/m | |
| | | | | | | 004H | 0 to 2000 mS/m | |
| | | | | TDC conversion (a/L) | | 000H | 0.0 to 20.0 g/L | |
| | | | | TDS conversion (g/L) | | 001H | 0 to 200 g/L | |
| | | | | Convetor colinity (0/) | | 002H | 0 to 500 g/L 0.00 to 4.00% | |
| | | | | Seawater salinity (%) | | 000H | ł | |
| | | | | NaCl salinity (%) | U | 000H | 0.00 to 20.00% | |
| | | | | W/h O | 44 | 0.0/ | to colorate d | |
| | | | | When Sensor cell cons | | | | |
| | | | | Unit | | Data | Measurement Range | |
| | | | | Conductivity (mS/cm) | | 000H | 0.0 to 200.0 mS/cm 0.0 to 500.0 mS/cm | |
| | | | | Conductivity (m5/cm) | | 001H | 0.0 to 2000 mS/cm | |
| | | | | | | 002H | | |
| | | | | Conductivity (C/m) | | 000H | 0.00 to 20.00 S/m | |
| | | | | Conductivity (S/m) | | 001H | 0.00 to 50.00 S/m | |
| | | | | | | 002H | 0.0 to 200.0 S/m | |
| | | | | TDC conversion (a/l) | 0000l onversion (g/L) 0001l | | 0 to 200 g/L | |
| | | | | TOS CONVERSION (g/L) | | | 0 to 500 g/L | |
| | | | | Convetor callaity (0/) | | 002H | 0 to 2000 g/L | |
| | | | | Seawater salinity (%) | | 000H | 0.00 to 4.00% | |
| | | | | NaCl salinity (%) | 1 00 |)00H | 0.00 to 20.00% | |
| | | | | | | | | |

| Shinko Command Type | Modbus Function Code | | Data Item | | | | Data | | |
|---------------------------|----------------------------|---------|--|---|--|----------|--------------------------------------|------|--|
| 50H/20H | 06H/03H | 0004H | Measurement range | | | | | | |
| | | | (FEB-102-ECM) | | | | | | |
| | | | ` | Measurement range will be fixed depending on the sele | | | | | |
| | | | sensor cell consta | | | | | | |
| | | | · | Negative acknowledgement (*) will be returned for the setting | | | | | |
| | | | command. | Cell | | | Magauramant | | |
| | | | Unit | Constant | : If | tem | Measurement Range | | |
| | | | | 0.01/cm | | 000H | 0.00 to 20.00 µS/cm | | |
| | | | Conductivity | 0.1/cm | 00 | 001H | 0.0 to 200.0 <i>\mu</i> S/cm | | |
| | | | (µS/cm) | 1.0/cm | 00 | 002H | 0 to 2000 \(\mu \text{S/cm} \) | | |
| | | | | 0.01/cm | - | D00H | 0.000 to 2.000 mS/m | | |
| | | | Conductivity | 0.1/cm | _ | 001H | 0.00 to 20.00 mS/m | | |
| | | | (mS/m) | 1.0/cm | | 002H | 0.0 to 200.0 mS/m | | |
| | | | | 0.01/cm | | 000H | 0.0 to 20.0 mg/L | | |
| | | | TDS conversion | 0.1/cm | _ | 001H | 0 to 200 mg/L | | |
| | | | (mg/L) | 1.0/cm | _ | 002H | 0 to 2000 mg/L | | |
| | | | (*) Frror code 1 (31H) | | _ | | otion code 1 (01H) (Modbus | | |
| | | | protocol) will be re | | .0001) (| от шлоор | alon dode i (o ii i) (modbae | | |
| 50H/20H | 06H/03H | 0005H | · · · · · · · · · · · · · · · · · · · | | Set v | alue. D | ecimal point ignored. | | |
| 50H/20H | 06H/03H | | | | | | ecimal point ignored. | | |
| | | ; ; | time constant | | | | | | |
| 50H/20H | 06H/03H | 0009H | Conductivity input ser | nsor | Set v | alue, D | ecimal point ignored. | | |
| | | | correction | | | | | | |
| 50H/20H | 06H/03H | 000AH | RTD type | | | H: Pt10 | | | |
| 5011/2011 | 0011/0011 | 000011 | Tamanawati wa aawa a | | | H: Pt10 | | | |
| 50H/20H | 06H/03H | UUUBH | Temperature comper method | , | | 102-EC | , | NaCl | |
| | | 1 | Helilou | | 0000H: Temperature characteristics of NaCl 0001H: Temperature coefficient (%/°C) and | | | | |
| | | 1 | | | randomly selected reference temperature | | | | |
| | | | | | 0002H: No temperature compensation | | | | |
| | | 1 | | | (FEB-102-ECM) | | | | |
| | | | | ` | 0000H: Temperature characteristics of NaCl | | | | |
| | | | | | 0001H: Temperature coefficient (%/°C) and | | | | |
| | | | | r | randomly selected reference temperature | | | | |
| | | | | 00 | 0002H: Temperature characteristics of | | | | |
| | | | | | pure (deionized) water | | | | |
| E011/0011 | 0011/0011 | 000011 | T | | 0003H: No temperature compensation | | | | |
| 50H/20H | | , | Temperature coefficie | | | | ecimal point ignored. | | |
| 50H/20H 50H/20H | | 1 | Reference temperatu Decimal point place | | | | ecimal point ignored. decimal point | | |
| 30H/20H | 001/0311 | OUUER | Decimal point place | | | | git after decimal point | | |
| 50H/20H | 06H/03H | 000FH | Pt100 input wire type | | | | ire type | | |
| | | | | (| | | ire type | | |
| 50H/20H | | | Cable length correction | | | | ecimal point ignored. | | |
| 50H/20H | | | Cable cross-section a | | | | ecimal point ignored. | | |
| 50H/20H | 06H/03H | 0012H | Temperature input filt time constant | er S | Set v | alue, D | ecimal point ignored. | | |
| 50H | 06H | 0013H | | on (| กกกกเ | H Cor | nductivity/Temperature | | |
| 3011 | 0011 | 00 1011 | mode | 011 | 2000 | | play Mode | | |
| | | | | (| 00011 | | nperature calibration mod | е | |
| 50H/20H | 06H/03H | 0014H | Temperature calibratio | | | | ecimal point ignored. | | |

| Shinko Command Type | Modbus Function Code | Data Item | | Data |
|---------------------------|---|-----------|------------------------------------|--|
| 50H | | 0015H | Conductivity calibration mode | 0000H: Conductivity/Temperature |
| | • | | | Display Mode |
| | | | | 0001H: Conductivity calibration |
| | | | | mode Zero adjustment |
| | | | | 0002H: Conductivity calibration |
| | | | | mode Span adjustment |
| 50H/20H | 06H/03H | | value | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0017H | Conductivity Span adjustment value | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0019H | EVT1 type | 0000H: No action 0001H: Conductivity input low limit 0002H: Conductivity input high limit 0003H: Temperature input low limit 0004H: Temperature input high limit 0005H: Error output 0006H: Fail output 0007H: Conductivity input error alarm output |
| 50H/20H | 06H/03H | 001AH | EVT1 value | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 001BH | EVT1 proportional band | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 001CH | EVT1 reset | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 001DH | EVT1 hysteresis type | 0000H: Medium value |
| | | | | 0001H: Reference value |
| 50H/20H | 06H/03H | 001EH | EVT1 ON side | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 001FH | EVT1 OFF side | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0020H | EVT1 ON delay time | Set value |
| 50H/20H | 06H/03H | 0021H | EVT1 OFF delay time | Set value |
| 50H/20H | 06H/03H | 0022H | EVT1 proportional cycle | Set value |
| 50H/20H | 06H/03H | 0023H | EVT1 output high limit | Set value |
| 50H/20H | 06H/03H | 0024H | EVT1 output low limit | Set value |
| 50H/20H | | | Output ON time when EVT1 output ON | Set value |
| 50H/20H | 06H/03H | | EVT1 output ON | Set value |
| 50H/20H | 06H/03H | 0027H | EVT2 type | 0000H: No action 0001H: Conductivity input low limit |
| | | | 5)(70 | 0002H: Conductivity input high limit 0003H: Temperature input low limit 0004H: Temperature input high limit 0005H: Error output 0006H: Fail output 0007H: Conductivity input error alarm output |
| 50H/20H | | | EVT2 value | Set value, Decimal point ignored. |
| 50H/20H | | | EVT2 proportional band | Set value, Decimal point ignored. |
| 50H/20H | | ī | EVT2 reset | Set value, Decimal point ignored. |
| 50H/20H | | | EVT2 hysteresis type | 0000H: Medium value 0001H: Reference value |
| 50H/20H | | | EVT2 ON side | Set value, Decimal point ignored. |
| 50H/20H | | | EVT2 OFF side | Set value, Decimal point ignored. |
| 50H/20H | | | EVT2 ON delay time | Set value |
| 50H/20H | | | EVT2 OFF delay time | Set value |
| 50H/20H | | | EVT2 proportional cycle | Set value |
| 50H/20H | | | EVT2 output high limit | Set value |
| 50H/20H | 06H/03H | 0032H | EVT2 output low limit | Set value |

| Shinko Command Type | Modbus Function Code | | Data Item | Data |
|---------------------------|----------------------------|-------|-------------------------------------|--|
| 50H/20H | 06H/03H | 0033H | Output ON time when EVT2 output ON | Set value |
| 50H/20H | 06H/03H | 0034H | Output OFF time when EVT2 output ON | Set value |
| | 06H/03H | | , · | 0000H: No action 0001H: Conductivity input low limit 0002H: Conductivity input high limit 0003H: Temperature input low limit 0004H: Temperature input high limit 0005H: Error output 0006H: Fail output 0007H: Conductivity input error alarm output |
| 50H/20H | | | EVT3 value | Set value, Decimal point ignored. |
| 50H/20H | | | EVT3 proportional band | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0038H | EVT3 reset | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0039H | EVT3 hysteresis type | 0000H: Medium value 0001H: Reference value |
| 50H/20H | 06H/03H | 003AH | EVT3 ON side | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 003BH | EVT3 OFF side | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 003CH | EVT3 ON delay time | Set value |
| 50H/20H | 06H/03H | 003DH | EVT3 OFF delay time | Set value |
| 50H/20H | 06H/03H | 003EH | EVT3 proportional cycle | Set value |
| 50H/20H | 06H/03H | 003FH | EVT3 output high limit | Set value |
| 50H/20H | 06H/03H | 0040H | EVT3 output low limit | Set value |
| 50H/20H | 06H/03H | 0041H | Output ON time when EVT3 output ON | Set value |
| 50H/20H | 06H/03H | 0042H | Output OFF time when EVT3 output ON | Set value |
| 50H/20H | | | EVT4 type | 0000H: No action 0001H: Conductivity input low limit 0002H: Conductivity input high limit 0003H: Temperature input low limit 0004H: Temperature input high limit 0005H: Error output 0006H: Fail output 0007H: Conductivity input error alarm output |
| 50H/20H | 06H/03H | 0044H | EVT4 value | Set value, Decimal point ignored. |
| 50H/20H | | | EVT4 proportional band | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0046H | EVT4 reset | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0047H | EVT4 hysteresis type | 0000H: Medium value 0001H: Reference value |
| 50H/20H | 06H/03H | 0048H | EVT4 ON side | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0049H | EVT4 OFF side | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 004AH | EVT4 ON delay time | Set value |
| 50H/20H | 06H/03H | 004BH | EVT4 OFF delay time | Set value |
| 50H/20H | 06H/03H | 004CH | EVT4 proportional cycle | Set value |
| 50H/20H | 06H/03H | 004DH | EVT4 output high limit | Set value |
| 50H/20H | 06H/03H | 004EH | EVT4 output low limit | Set value |
| 50H/20H | | | Output ON time when EVT4 output ON | Set value |
| 50H/20H | 06H/03H | 0050H | Output OFF time when EVT4 output ON | Set value |

| Shinko Command Type | Modbus Function Code | | | Data |
|---------------------------|----------------------------|--------|--|--|
| 50H/20H | 06H/03H | 0051H | Transmission output 1 type | 0000H: Conductivity transmission 0001H: Temperature transmission |
| | | | | 0002H: EVT1 MV transmission |
| | | | | 0003H: EVT2 MV transmission |
| 50H/20H | 06H/03H | | 1 9 | Set value, Decimal point ignored. |
| 50H/20H | | | Transmission output 1 low limit | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0054H | Transmission output 2 type | 0000H: Conductivity transmission |
| | | | | 0001H: Temperature transmission 0002H: EVT1 MV transmission |
| | | | | 0003H: EVT2 MV transmission |
| | | | | 0004H: EVT3 MV transmission |
| 50H/20H | 06H/03H | 0055H | Transmission output 2 | Set value, Decimal point ignored. |
| | | | high limit | pentiguesa. |
| 50H/20H | 06H/03H | 0056H | Transmission output 2 low limit | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0060H | Set value lock | 0000H: Unlock |
| | | | | 0001H: Lock 1 |
| | | | | 0002H: Lock 2 |
| | | | | 0003H: Lock 3 |
| 50H/20H | 06H/03H | 0061H | Display selection | 0000H: Input value |
| | | | | (Conductivity, Temperature) |
| | | | | 0001H: Conductivity |
| 5011/0011 | 0011/0011 | 000011 | | 0002H: Temperature |
| 50H/20H | 06H/03H | 0063H | ' ' | 0000H: Enabled |
| E011/2011 | 0011/0011 | 000411 | OCCUI | 0001H: Disabled |
| 50H/20H | 06H/03H | 0064H | Temperature Display when no temperature compensation | 0000H: Unlit |
| | | | temperature compensation | 0001H: Reference temperature 0002H: Measurement value |
| 50H | 06H | 007FH | Key operation change flag | 0001H: Clear change flag |
| 0011 | 0011 | 007111 | clearing | - coc i iii cicai ciiange nag |
| 50H/20H | 06H/03H | 0102H | • | 0000H: Last value HOLD |
| | | | when calibrating | 0001H: Set value HOLD |
| | | | | 0002H: Measurement value |
| 50H/20H | 06H/03H | 0103H | Transmission output 1 Set value HOLD | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0104H | Transmission output 2 status | 0000H: Last value HOLD |
| | | | when calibrating | 0001H: Set value HOLD |
| | | | | 0002H: Measurement value |
| 50H/20H | 06H/03H | 0105H | Transmission output 2 Set value HOLD | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0106H | EVT1 conductivity input error | 0000H: No action |
| | | | alarm EVT□ type | 0001H: EVT2 type |
| | | | | 0002H: EVT3 type |
| | | | | 0003H: EVT4 type |
| 50H/20H | 06H/03H | 0107H | EVT2 conductivity input error | 0000H: EVT1 type |
| | | | alarm EVT□ type | 0001H: No action |
| | | | | 0002H: EVT3 type |
| | | | | 0003H: EVT4 type |
| 50H/20H | 06H/03H | 0108H | EVT3 conductivity input error | 0000H: EVT1 type |
| | | | alarm EVT□ type | 0001H: EVT2 type |
| | | | | 0002H: No action |
| | | | | 0003H: EVT4 type |

| Shinko Command Type | Modbus Function Code | | Data Item | Data |
|---------------------------|----------------------------|-------|---|--|
| 50H/20H | | 0109H | EVT4 conductivity input error alarm EVT□ type | 0000H: EVT1 type 0001H: EVT2 type 0002H: EVT3 type 0003H: No action |
| 50H/20H | 06H/03H | 010AH | EVT1 conductivity input error alarm span when EVT□ output ON | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 010BH | EVT1 conductivity input error alarm time when EVT□ output ON | Set value |
| 50H/20H | 06H/03H | 010CH | EVT1 conductivity input error alarm span when EVT□ output OFF | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 010DH | EVT1 conductivity input error alarm time when EVT□ output OFF | Set value |
| 50H/20H | 06H/03H | 010EH | EVT2 conductivity input error alarm span when EVT□ output ON | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 010FH | EVT2 conductivity input error alarm time when EVT□ output ON | Set value |
| 50H/20H | 06H/03H | 0110H | | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0111H | EVT2 conductivity input error alarm time when EVT□ output OFF | Set value |
| 50H/20H | 06H/03H | 0112H | EVT3 conductivity input error alarm span when EVT□ output ON | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0113H | EVT3 conductivity input error alarm time when EVT□ output ON | Set value |
| 50H/20H | 06H/03H | 0114H | EVT3 conductivity input error alarm span when EVT□ output OFF | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0115H | EVT3 conductivity input error alarm time when EVT□ output OFF | Set value |
| 50H/20H | 06H/03H | 0116H | EVT4 conductivity input error alarm span when EVT□ output ON | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0117H | EVT4 conductivity input error alarm time when EVT□ output ON | Set value |
| 50H/20H | 06H/03H | 0118H | EVT4 conductivity input error alarm span when EVT□ output OFF | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0119H | EVT4 conductivity input error alarm time when EVT□ output OFF | Set value |
| 50H/20H | 06H/03H | 011AH | Conductivity input error alarm time unit | 0000H: Seconds 0001H: Minutes |
| 50H | 06H | 011BH | Transmission output 1 adjustment mode | 0000H: Conductivity/Temperature Display Mode 0001H: Transmission output 1 Zero adjustment mode 0002H: Transmission output 1 Span adjustment mode |
| 50H/20H | | 011CH | adjustment value | Set value, Decimal point ignored. |
| 50H/20H | | | Transmission output 1 Span adjustment value | Set value, Decimal point ignored. |
| 50H | 06H | 011EH | Transmission output 2 adjustment mode | 0000H: Conductivity/Temperature Display Mode 0001H: Transmission output 2 Zero adjustment mode 0002H: Transmission output 2 Span adjustment mode |
| 50H/20H | 06H/03H | 011FH | adjustment value | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0120H | Transmission output 2 Span adjustment value | Set value, Decimal point ignored. |

| Shinko Command Type | Modbus Function Code | Data Item | | Data |
|---------------------------|----------------------------|-----------|---------------------------|-----------------------------------|
| 50H/20H | 06H/03H | 0121H | EVT1 cycle variable range | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0122H | EVT2 cycle variable range | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0123H | EVT3 cycle variable range | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0124H | EVT4 cycle variable range | Set value, Decimal point ignored. |
| 50H/20H | 06H/03H | 0125H | EVT1 cycle extended time | Set value |
| 50H/20H | 06H/03H | 0126H | EVT2 cycle extended time | Set value |
| 50H/20H | 06H/03H | 0127H | EVT3 cycle extended time | Set value |
| 50H/20H | 06H/03H | 0128H | EVT4 cycle extended time | Set value |
| 50H/20H | 06H/03H | 0200H | User save area 1 | -32768 to 32767 (8000H to 7FFFH) |
| 50H/20H | 06H/03H | 0201H | User save area 2 | -32768 to 32767 (8000H to 7FFFH) |
| 50H/20H | 06H/03H | 0202H | User save area 3 | -32768 to 32767 (8000H to 7FFFH) |
| 50H/20H | 06H/03H | 0203H | User save area 4 | -32768 to 32767 (8000H to 7FFFH) |
| 50H/20H | 06H/03H | 0204H | User save area 5 | -32768 to 32767 (8000H to 7FFFH) |
| 50H/20H | 06H/03H | 0205H | User save area 6 | -32768 to 32767 (8000H to 7FFFH) |
| 50H/20H | 06H/03H | 0206H | User save area 7 | -32768 to 32767 (8000H to 7FFFH) |
| 50H/20H | 06H/03H | 0207H | User save area 8 | -32768 to 32767 (8000H to 7FFFH) |
| 50H/20H | 06H/03H | 0208H | User save area 9 | -32768 to 32767 (8000H to 7FFFH) |
| 50H/20H | 06H/03H | 0209H | User save area 10 | -32768 to 32767 (8000H to 7FFFH) |

7.3 Read Only Command

| Shinko | Modbus | | | • | | | _ , | | |
|-----------------|--------|-------|---|---|-----------------|-------------------------|--|--|--|
| Command Type | Code | | Data Item | | | | Data | | |
| 20H | 03H | 0080H | Conductivity | | | | Conductivity, Decimal point ignored. | | |
| 20H | 03H | | Status flag 1 | | | | , , | | |
| | | | 0000 0000 | 0000 | 000 | | | | |
| | | | 2 ¹⁵ to |) | 2 | 0 | | | |
| | | | 2 ⁰ digit: Not us | ed (Al | ways | 0) | | | |
| | | | 2 ¹ digit: Not us | ed (Al | ways | 0) | | | |
| | | | 2 ² digit: Not us | | | | | | |
| | | | 2 ³ digit: Not us | | | | | | |
| | | | 2 ⁴ digit: Not us | | | | | | |
| | | | 2 ⁵ digit: Tempe | erature | | | d. Dumant | | |
| | | | 2 ⁶ digit: Tempe | rature | | Normal or short-cire | 1: Burnout | | |
| | | | 2 digit. rempe | rature | | Normal | 1: Short-circuited | | |
| | | | 2 ⁷ digit: Outsid | e tem | | | isation range: Exceeding 110.0℃ | | |
| | | | g | | | Normal | 1: Exceeding 110.0℃ | | |
| | | | 2 ⁸ digit: Outsid | 2 ⁸ digit: Outside temperature compensation range: Less than 0.0°C | | | | | |
| | | | | | | Normal | 1: Less than 0.0°C | | |
| | | | | | | | , salinity (FEB-102-ECH), or | | |
| | | | TDS co | nvers | | | e measurement range (high limit) | | |
| | | | Old digits Cond. | | | Normal | 1: Outside the range (high limit) | | |
| | | | | | | | e, salinity (FEB-102-ECH), or ne measurement range (low limit) | | |
| | | | 100 0 | OHVE | | s outside ti | 1: Outside the range (low limit) | | |
| | | | 2 ¹¹ digit: Unit s | tatus | | | //Temperature Display Mode | | |
| | | | J | | | Setting mod | · · · · · · · · · · · · · · · · · · · | | |
| | | | 2 ¹² , 2 ¹³ digits: 0 | Condu | ıctivity | | | | |
| | | | | 2 ¹³ | 2 ¹² | | Status | | |
| | | | _ | 0 | 0 | | vity/Temperature Display mode | | |
| | | | | 0 | 1 | • | ero adjustment in Conductivity | | |
| | | | - | 1 | 0 | calibration | pan adjustment in Conductivity | | |
| | | | | 1 | U | calibration | | | |
| | | ; | 2 ¹⁴ digit: Not us | sed (A | lways | | | | |
| | | | 2 ¹⁵ digit: Chang | | | | 0: No 1: Yes | | |
| 20H | 03H | 0084H | EVT1 MV | | | | MV, Decimal point ignored. | | |
| 20H | 03H | | EVT2 MV | | | | MV, Decimal point ignored. | | |
| 20H | 03H | | EVT3 MV | | | | MV, Decimal point ignored. | | |
| 20H | 03H | 0087H | EVT4 MV | | | | MV, Decimal point ignored. | | |

| Shinko Command Type | Modbus Function Code | | D | ata Ite | m | Data |
|---------------------------|----------------------------|-------|--|------------------------|---------------------------|-------------------------------------|
| 20H | 03H | 0090H | Temperatu | re | | Temperature, Decimal point ignored. |
| 20H | 03H | 0091H | Status flag | 2 | | |
| | | | 0000 000 2 ¹⁵ | 0 00 to | 00 0000 2 ⁰ | |
| | | | 20 digit: EV | T1 ou | tput 0: OFF | 1: ON |
| | | | 2 ¹ digit: EV | T2 ou | tput 0: OFF | 1: ON |
| | | | 2 ² digit: EV | T3 ou | tput 0: OFF | 1: ON |
| | | | 2 ³ digit: EV | | | 1: ON |
| | | | 2 ⁴ , 2 ⁵ digits | | smission output 1 | adjustment status flag |
| | | | 2 ⁵ | 2 ⁴ | | Status |
| | | | 0 | 0 | Conductivity/Tem | perature Display Mode |
| | | | 0 | 1 | During Transmiss | sion output 1 Zero adjustment in |
| | | | <u> </u> | | Transmission out | tput 1 adjustment mode |
| | | | 1 | 0 | • | sion output 1 Span adjustment in |
| | | | | | Transmission out | tput 1 adjustment mode |
| | | | | : Trar | smission output 2 | adjustment status flag |
| | | | 2 ⁷ | 2 ⁶ | | Status |
| | | | 0 | 0 | • | perature Display Mode |
| | | | 0 | 1 | • | sion output 2 Zero adjustment in |
| | | | | | | tput 2 adjustment mode |
| | | | 1 | 0 | • | sion output 2 Span adjustment in |
| | | | <u> </u> | | Transmission out | tput 2 adjustment mode |
| | | | | | ot used (Always 0) | |
| | | | 2 ¹² , 2 ¹³ dig | its: Ter | mperature calibrati | on status flag |
| | | | 2 ¹³ | 2 ¹² | | Status |
| | | | 0 | 0 | • | perature Display Mode |
| | | | 0 | 1 | During Temperat | ure calibration mode |
| | | | 2 ¹⁴ , 2 ¹⁵ dig | its: No | t used (Always 0) | |

7.4 Conductivity Calibration, Temperature Calibration and Transmission Output Adjustment via Communication Command

7.4.1 Conductivity Calibration

Cell constant may vary due to deterioration of the 4-electrode/2-electrode conductivity sensor.

To correct the varied cell constant, calibration must be performed.

Calibrate Conductivity Zero adjustment first, followed by Conductivity Span adjustment.

The following outlines the procedure for conductivity calibration.

(1) Conductivity zero adjustment

When selecting Last value HOLD (0000H) at Data item 0102H (Transmission output 1 status when calibrating) or at Data item 0104H (Transmission output 2 status when calibrating), select it while the 4-elctrode/2-elctrode conductivity sensor is being immersed in the solution currently calibrated.

After that, immerse the sensor in the 1st point standard solution (pH 7).

- 2 At this stage, do not immerse the 4-elctrode conductivity sensor in the standard solution.
- 3 Set Data item 0015H (Conductivity calibration mode) to 0001H. The unit moves to Conductivity calibration Zero adjustment mode.
- 4 Set the Conductivity Zero adjustment value at Data item 0016H (Conductivity Zero adjustment value) so that conductivity becomes 0 (zero).

When conductivity is 0 (zero), it is not necessary to adjust.

- ⑤ If 2¹³, 2¹² digits are read at Data item 0081H (Status flag 1), 01 (During Zero adjustment in Conductivity calibration mode) will be returned.
- Set Data item 0015H (Conductivity calibration mode) to 0000H.
 Conductivity Zero adjustment is complete, and the unit will revert to Conductivity/Temperature Display mode.

(2) Conductivity span adjustment

- 1 Immerse the 4-elctrode conductivity sensor in the standard solution.
- 2 Set Data item 0015H (Conductivity calibration mode) to 0002H.

The unit moves to Conductivity calibration Span adjustment mode.

- 3 Set the Conductivity Span adjustment value at Data item 0017H (Conductivity Span adjustment value), while checking the conductivity.
- 4 If 2¹³, 2¹² digits are read at Data item 0081H (Status flag 1), 10 (During Span adjustment in Conductivity calibration mode) will be returned.
- Set Data item 0015H (Conductivity calibration mode) to 0000H.
 Conductivity Span adjustment is complete, and the unit will revert to Conductivity/Temperature Display mode.

If Conductivity calibration cannot be performed while in Conductivity calibration mode due to temperature compensation error, Conductivity measured value error, etc., Error code 1 (Burnout, Short-circuited, etc.) will be returned after 2⁵ to 2¹⁰ digits are read at Data item 0081H. To cancel the error code, set Data item 0015H (Conductivity calibration mode) to 0000H. The unit will revert to Conductivity/Temperature Display Mode.

If Conductivity Zero/Span adjustment value is set at Data item 0016H (Conductivity Zero adjustment value) or 0017H (Conductivity Span adjustment value) in Conductivity/Temperature Display Mode, the following error code will be returned.

- Shinko protocol: Error code 34H
- Modbus protocol: Exception code 11H

7.4.2 Temperature Calibration

Temperature calibration is performed by setting temperature calibration value.

When a sensor cannot be set at the exact location where measurement is desired, the resulting measured temperature may deviate from the temperature in the desired location. In this case, the desired temperature can be set for the desired location by setting a temperature calibration value. However, it is effective within the input rated range regardless of the temperature calibration value.

Temperature after temperature calibration = Current temperature + (Temperature calibration value)

(e.g.) When current temperature is 23.5°C,

When temperature calibration value is set to 1.5° C: $23.5 + (1.5) = 25.0^{\circ}$ C When temperature calibration value is set to -1.5° C: $23.5 + (-1.5) = 22.0^{\circ}$ C

The following outlines the procedure for Temperature calibration.

- ① Set Data item 0013H (Temperature calibration mode) to 0001H. The unit moves to Temperature Calibration mode.
- 2 Set the Temperature calibration value at Data item 0014H (Temperature calibration value).
- ③ If 2¹³, 2¹² digits are read at Data item 0091H, 01 (During Temperature calibration mode) will be returned.
- Set Data item 0013H (Temperature calibration mode) to 0000H.
 Temperature calibration is complete, and the unit will revert to Conductivity/Temperature Display mode.

If Temperature calibration cannot be performed while calibrating temperature due to input error, calibration value error, etc., Error code 1 (Burnout, Short-circuited, etc.) will be returned after 2⁵ to 2⁸ digits are read at Data item 0081H.

To cancel the error code, set Data item 0013H (Temperature calibration mode) to 0000H. The unit will revert to Conductivity/Temperature Display Mode.

If Temperature calibration value is set at Data item 0014H (Temperature calibration value) in Conductivity/Temperature Display Mode, the following error code will be returned.

Shinko protocol: Error code 34H Modbus protocol: Exception code 11H

7.4.3 Transmission Output 1 Adjustment

Fine adjustment of Transmission output 1 is performed.

This instrument is adjusted at the factory, however, differences may occur between the indication value of the connected equipment (recorders, etc.) and output value of this instrument.

In this case, perform Transmission output 1 Zero adjustment and Span adjustment.

The following outlines the procedure for Transmission output 1 adjustment.

- ① Set Data item 011BH (Transmission output 1 adjustment mode) to 0001H.

 The unit moves to Transmission output 1 Zero adjustment mode.
 - If 2^5 , 2^4 digits are read at Data item 0091H (Status flag 2), 01 (During Transmission output 1 Zero adjustment in Transmission output 1 adjustment mode) will be returned.
- ② Set the Transmission output 1 Zero adjustment value at Data item 011CH (Transmission output 1 Zero adjustment value), while viewing the value indicated on the connected equipment (recorders, etc.).

Setting range: ±5.00% of Transmission output span

- ③ Set Data item 011BH (Transmission output 1 adjustment mode) to 0002H.
 - The unit moves to Transmission output 1 Span adjustment mode.
 - If 2^5 , 2^4 digits are read at Data item 0091H (Status flag 2), 10 (During Transmission output 1 Span adjustment in Transmission output 1 adjustment mode) will be returned.
- ⁽⁴⁾ Set the Transmission output 1 Span adjustment value at Data item 011DH (Transmission output 1 Span adjustment value), while viewing the value indicated on the connected equipment (recorders, etc.).

Setting range: ±5.00% of Transmission output span

- 5 Repeat steps 1 to 4 if necessary.
- 6 To finish the Transmission output 1 adjustment, set Data item 011BH (Transmission output 1 adjustment mode) to 0000H.

The unit reverts to Conductivity/Temperature Display Mode.

7.4.4 Transmission Output 2 Adjustment

Fine adjustment of Transmission output 2 is performed.

This instrument is adjusted at the factory, however, differences may occur between the indication value of the connected equipment (recorders, etc.) and output value of this instrument.

In this case, perform Transmission output 2 Zero adjustment and Span adjustment.

The following outlines the procedure for Transmission output 2 adjustment.

- 1) Set Data item 011EH (Transmission output 2 adjustment mode) to 0001H.

 The unit moves to Transmission output 2 Zero adjustment mode.
 - If 2⁷, 2⁶ digits are read at Data item 0091H (Status flag 2), 01 (During Transmission output 2 Zero adjustment in Transmission output 2 adjustment mode) will be returned.
- ② Set the Transmission output 2 Zero adjustment value at Data item 011FH (Transmission output 2 Zero adjustment value), while viewing the value indicated on the connected equipment (recorders, etc.).

Setting range: ±5.00% of Transmission output span

- ③ Set Data item 011EH (Transmission output 2 adjustment mode) to 0002H.
 - The unit moves to Transmission output 2 Span adjustment mode.
 - If 2^7 , 2^6 digits are read at Data item 0091H (Status flag 2), 10 (During Transmission output 2 Span adjustment in Transmission output 2 adjustment mode) will be returned.
- ④ Set the Transmission output 2 Span adjustment value at Data item 0120H (Transmission output 2 Span adjustment value), while viewing the value indicated on the connected equipment (recorders, etc.).

Setting range: ±5.00% of Transmission output span

- 5 Repeat steps 1 to 4 if necessary.
- 6 To finish the Transmission output 2 adjustment, set Data item 011EH (Transmission output 2 adjustment mode) to 0000H.

The unit reverts to Conductivity/Temperature Display Mode.

7.5 Notes on Programming Monitoring Software

7.5.1 How to speed up the scan time

When monitoring multiple units of FEB-102-EC, set the program so that the requisite minimum pieces of data such as Data item 0080H (Conductivity), Data item 0090H (Temperature), Data item 0081H (Status flag 1), Data item 0091H (Status flag 2) can be read. For other data, set the program so that they can be read only when their set value has been changed. This will speed up the scan time.

7.5.2 How to read the set value changes made by the front keypad operation

If any set value is changed by keypad operation, the FEB-102-EC \square will set [0081H (Status flag 1) 2¹⁵: Change in key operation] to 1 (Yes).

There are 2 methods of reading the set value changes made by the front keypad.

(1) Reading method 1

- ① On the monitoring software side, check that [0081H (Status flag 1) 2¹⁵: Change in key operation] has been set to 1 (Yes), then read all set values.
- ② Clear [0081H (Status flag 1) 2¹⁵: Change in key operation], by setting Data item 007FH (Key operation change flag clearing) to 0001H (Clear change flag).
 If 007FH (Key operation change flag clearing) is set to 0001H (Clear change flag) during setting mode of the instrument, Error code 5 (35H, Shinko protocol) or Exception Code 18 (12H, Modbus protocol) will be returned as a negative acknowledgement. And [0081H (Status flag 1) 2¹⁵: Change in key operation] cannot be cleared.
 - Set a program so that all set values can be read when a negative acknowledgement is returned.
- 3 Read all set values again after acknowledgement is returned.

(2) Reading method 2

- ① On the monitoring software side, check that [0081H (Status flag 1) 2¹⁵: Change in key operation] has been set to 1 (Yes), then set 007FH (Key operation change flag clearing) to 0001H (Clear change flag).
- ② Set the program depending on acknowledgement or negative acknowledgement as follows. When acknowledgement is returned:

Consider it as settings completed, and read all set values.

When Error code 5 (35H, Shinko protocol) or Exception code 18 (12H, Modbus protocol) is returned as a negative acknowledgement:

Consider it as still in setting mode, and read the requisite minimum pieces of data such as 0080H (Conductivity), 0090H (Temperature), 0081H (Status flag 1), 0091H (Status flag 2), then return to step \bigcirc 1.

Thus, programs which do not affect the scan time can be created using the methods described above, even if set values on the monitoring software will not be updated until settings are complete.

7.5.3 Note when sending all set values at one time

• When changing EVT type at Data item 0019H (EVT1 type), 0027H (EVT2 type), 0035H (EVT3 type), 0043H (EVT4 type), the EVT1 to EVT4 values will default to 0 (zero).

The EVT output status will also be initialized.

First, send the EVT1, EVT2, EVT3, EVT4 type, then send the EVT1, EVT2, EVT3, EVT4 value at Data item 001AH (EVT1 value), 0028H (EVT2 value), 0036H(EVT3 value) and 0044H (EVT4 value).

8. Specifications

| Serial communication | The following oper | The following operations can be carried out from an external computer. | | | | | | |
|----------------------|--|--|---------------------------|--------------------------------|--|--|--|--|
| | (1) Reading and setting of various set values | | | | | | | |
| | (2) Reading of the conductivity, salinity conversion, temperature, or its status | | | | | | | |
| | (3) Function chang | je, adjustme | nt | | | | | |
| | (4) Reading and s | etting of use | r save area | | | | | |
| Cable length | 1.2 km (Max.), Cal | ole resistanc | e: Within 50 Ω | | | | | |
| | (Terminators are n | ot necessary | , but if used, use 120 9 | Ω or more on one side.) | | | | |
| Communication line | EIA RS-485 | | | | | | | |
| Communication method | Half-duplex comm | unication | | | | | | |
| Communication speed | 9600, 19200, 3840 | 00 bps (Sele | ctable by keypad) | | | | | |
| Synchronization | Start-stop synchron | nization | | | | | | |
| Code form | ASCII, Binary | | | | | | | |
| Communication | Shinko protocol, M | lodbus ASCI | I, Modbus RTU (Select | able by keypad) | | | | |
| protocol | | | | | | | | |
| Data bit/Parity | | | y, 8-bits/Even, 7-bits/Ev | en, 8-bits/Odd, | | | | |
| | 7-bits/Odd (Selecta | | | | | | | |
| Stop bit | 1 bit, 2 bits (Select | | | | | | | |
| Error correction | Command request | repeat syst | em | | | | | |
| Error detection | | • | ko protocol), LRC (Modl | ous protocol ASCII), | | | | |
| | CRC-16 (Modbus p | protocol RTU |) | | | | | |
| Data format | | | | | | | | |
| | Communication | | Modbus ASCII | Modbus RTU | | | | |
| | Protocol | Protocol | | | | | | |
| | Start bit | 1 | 1 | 1 | | | | |
| | Data bit | 7 | 7 | 8 | | | | |
| | Parity | Even | | No parity (Even, Odd) | | | | |
| | 0, 1,11 | 4 | Selectable | Selectable | | | | |
| | Stop bit | 1 | 1 (2) | 1 (2) | | | | |
| | | | Selectable | Selectable | | | | |

9. Troubleshooting

Check that power is being supplied to the master and slave that customers use. If communication failure still occurs, check the following.

| Problem | Possible Cause | Solution |
|----------------------------|--|--|
| Communication failure | Communication cable is not securely | Check the communication cable |
| | connected/disconnected or defective. | and connector. |
| | Incorrect wiring of the communication | Check the communication cable |
| | cable and connector | and connector. |
| | Imperfect contact between the | Check the communication cable |
| | communication cable and the | and connector. |
| | connector or communication connector and instrument port | |
| | Communication speed of the slave | Check the communication speed |
| | does not match that of the master. | of the slave and master. |
| | | |
| | The data bit, parity and stop bit of | Check the data bit, parity and |
| | the master do not correspond to | stop bit of the master and the |
| | those of the slave. | slave. |
| | The instrument number (address) | Check the instrument number |
| | of the slave does not correspond | (address) of the slave and |
| | to that of the command. | command. |
| | The instrument numbers | Check the instrument numbers |
| | (addresses) are duplicated in | (addresses) of the slave. |
| | multiple slaves. | |
| | Make sure that the program is | Check the program. |
| | appropriate for the transmission | |
| | timing. | |
| Although communication | A non-existent command code has | Check the command code. |
| is occurring, the response | been sent. | |
| is negative | The setting command data | Check the setting range of the |
| acknowledgement. | exceeds the setting range of the | slave. |
| | slave. | |
| | The FEB-102-EC□ cannot be set | Check the slave status. |
| | while calibration is being performed. | |
| | Refer to Sections 7.4.1 Conductivity | |
| | Calibration and 7.4.2 Temperature | |
| | Calibration (pp.23, 24). | |
| | The FEB-102-EC□ is in front keypad | Return the unit to Conductivity/ |
| | operation setting mode. | Temperature Display Mode. |
| | -p-:-allon oolling mode. | - 1- 1- 1- 1- 1- 1- 1- 1- 1- 1- 1- 1- 1- |

For all other malfunctions, please contact our main office or dealers.

SHINKO TECHNOS CO., LTD. OVERSEAS DIVISION

Head Office: 2-5-1, Senbahigashi, Minoo, Osaka, Japan

URL: http://www.shinko-technos.co.jp Tel: +81-72-727-6100 E-mail: overseas@shinko-technos.co.jp Fax: +81-72-727-7006